

MVIDIA®

Modern Graphics Engine Design

Sim Dietrich

NVIDIA Corporation

sim.dietrich@nvidia.com

Overview

- Modern Engine Features
- Modern Engine Challenges
- Scene Management
 - Culling & Batching
- Geometry Management
 - Collision Structures
- Shader Systems
- Example Engine Design



Modern Graphics Engine Features

- High polygon count for added visual complexity
 - Not just to make things 'smoother'
- Some form of bump mapping for more surface detail
 - From single-light dot3
 - To general diffuse / specular / aniso per-pixel lighting
- Some form of shadows
 - From simple blobby discs under characters
 - To full shadow map or shadow volume for each light



More Features

- Particle system for splashes, sparks, etc
- Decal System for blood, scorch marks, etc.
- Performance & Visual Scalability
 - Game should look good on the newer cards
 - 1280x1024 x 4X AA + 4X Aniso
 - Game should look 'ok' on the older cards
 - 800x600 x 2X AA
 - And run well on both at the appropriate resolution and Anti-Aliasing settings

Challenges

- To get achieve visually rich scenes, there must be several visually interesting objects
- To get acceptable frame rates, the number of draw calls in a frame should be low
 - < 500 per frame for good frame rates</p>
 - This is a CPU limitation
 - The API & Driver must do a little work every time you make a render call to draw something
 - Many calls doing a little CPU work add up to a lot of CPU work



Challenges

- Complexity
 - Modern engines are able to lose some complexity compared to engines a few years ago
 - Software Transform
 - Software Rasterization
 - But, there are plenty of new things to worry about
 - High poly-count worlds in low memory
 - Realistic characters & animation
 - Shader Management
 - High Framerates



Scene Mangement

- There are about 5 different game engine sections that need access to the geometry in the scene
- Culling
- Rendering
- Collision
- Decals
- \bigcirc Al



Scene Management

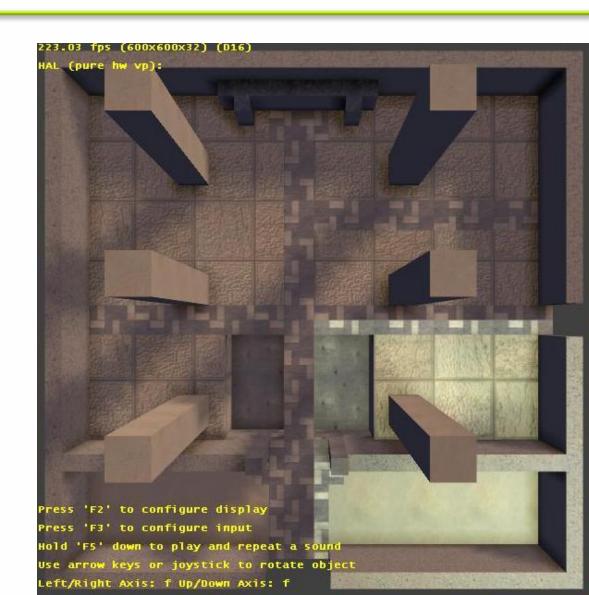
- Culling View Frustum Culling
 - Also from light's point of view for some shadow approaches
- Rendering
 - May need to render from multiple points of view for radar, shadows, etc.
- Collision
 - May be simplified version of the rendered geometry
- Decals
 - If these are done by re-rendering scene triangles, need per-triangle collision
- \bigcirc Al
 - The computer needs some spatial awareness
 - For path-finding, tactical understanding, etc.



- Goal : To quickly identify groups of triangles that can be culled out efficiently
 - Typically inside a bounding volume
 - BSP Leaf, Sphere, Bounding Box
- There is a tradeoff between culling efficiency and CPU efficiency:
 - The ultimate culling efficiency would cull each triangle individually
 - The ultimate CPU efficiency would draw the entire world in one draw call
- The trick is to group most of your scene in large, easyto-cull chunks

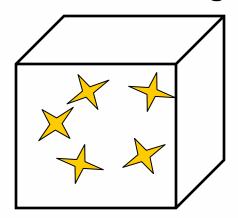


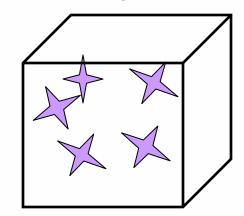
- In this scene, a world section is broken into a grid with ~300 triangle cells
- Highlighted area represents one such 3D Cell
- Probably too few tris for CPU batch efficiency



- Make bounding boxes too small, and clipping creates many extra triangles & vertices
- Make bounding boxes too large, and you end up sending down too much off-screen geometry
 - Can also create per-material AABoxes
- Instanced Geometry
 - Store a Axis-Aligned Bounding box, AA Cylinder or Sphere for each Instance for culling
 - Don't cull individual bone groups except for very expensive and close-to-camera characters

- Particle Systems
 - Store a bounding volume for each group of particles
 - Cull entire group as a unit
 - Also try to draw as a unit for efficiency
 - If particles don't affect gameplay, can also avoid calculating off-screen systems







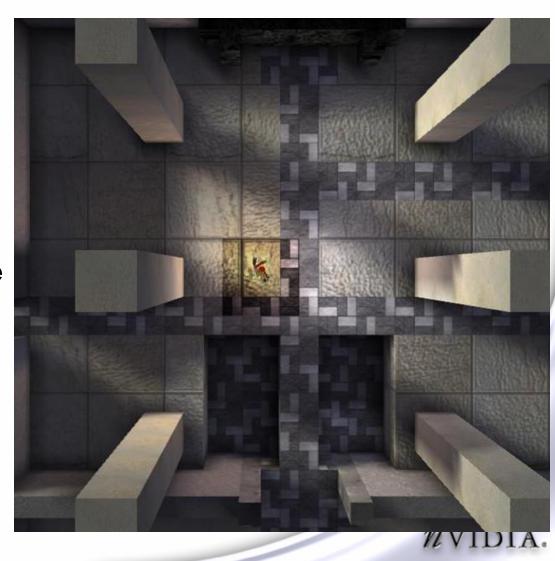
- There are several popular approaches for creating decals for bullet holes, scorch marks, blood drops, etc.
- One approach renders little pieces of geometry to represent the bullet hole, etc.
 - Upside : Low fillrate for small decals
 - Downside : Needs to be clipped so that it doesn't hang over a corner
 - Downside : May Z fight with geometry, need bias



- Another method uses texture mapping to apply the decal by re-rendering scene polygons with the texture applied
- Upside : No need to clip to corners
- Upside : No depth fighting if you use the exact same geometry as used for rendering
- Downside : Large polygons cost fillrate for many decals

- Either approach requires finding the exact triangles the decal touches
 - Either for clipping the geometry decals to the scene geometry
 - Or re-rendering them with the decal texture
- Therefore, the engine must support being able to quickly find a group of nearby polygons on which to apply the decal
- This has implications for the collision system...

- Highlighted area indicates triangles possibly covered by decal shadow
- Amount of extra fillrate burned is more for less-tessellated geometry
- So, more vertices can save fillrate on decals



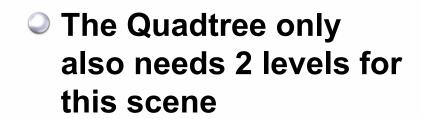
- Efficient collision with world & mesh data is a challenge in a modern engine
 - Many more polygons for required visual richness
- Standard BSP approaches won't cut it
 - Only for very simple walls & floors will a leaf-based BSP suffice
 - The more polygons in the scene, the greater the penalty for splits

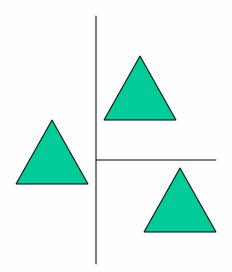


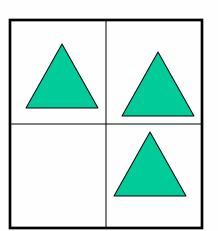
- One of the main problems with a standard BSP or KD-Tree (axis aligned BSP) is the depth of the tree
- Consider every time you follow a pointer, you can assume a CPU cache miss
 - The deeper your tree, the more cache misses you will take
 - Cache misses can be more expensive than intersection tests
 - Therefore, shallower tree types will perform better on high-polygon-count scenes
- Two ways to make a tree shallow :
 - High Branching Factor QuadTree, Octree
 - More children per node
 - Store multiple items in one Leaf



This KD-Tree or BSP has 2 levels, the leftmost root and the rightmost children

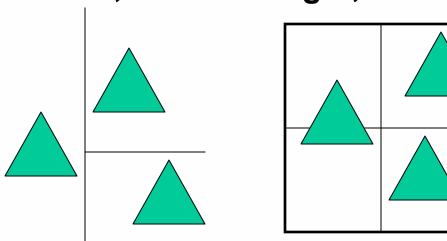


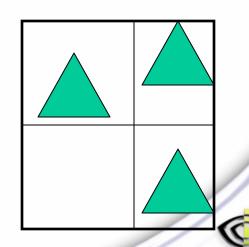






- Of course, if the scene is arranged differently, the KD tree or BSP tree can cope better by adjusting where the split planes go.
- Standard Quadtrees and Octrees don't do this, so require more levels. Variations with rectilinear cells, as on the right, can cope better

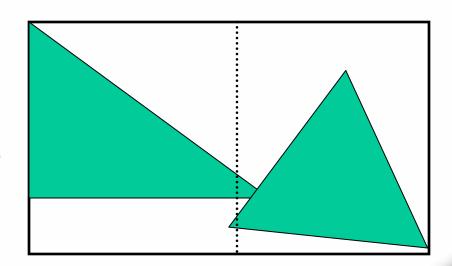




- An alternative is the Axis-Aligned Bounding Box Tree
 - Good example in Game Programming Gems 2
 - Also Short Tutorial on FlipCode
- This Tree contains a hierarchy of AA Bounding Boxes which contain all of the geometry
- The AABox Tree is not meant to represent empty space like a grid, but instead to just tightly contain the triangles

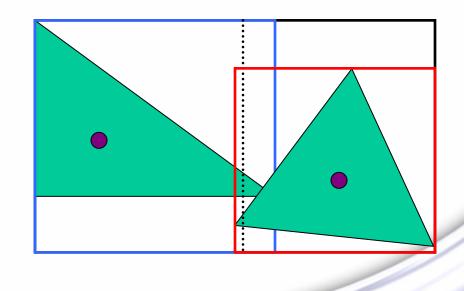
The basic idea is to somehow divide the # of triangles in a node in half at each step, but without clipping them to the Split Plane

- Root Node
- Dashed line is Split Plane





- The triangle centroid is compared to the 'Split Plane'
- This way each triangle only lives in one node
- No clipping to increase polycounts
 - Important for collision more than for rendering
 - Left Child in Blue
 - Right Child in Red
 - Dots are TriangleCentroids





- Each node in tree contains a Axis-Aligned Bounding box, and two children
- Each child may be a Node or a Leaf
- Leafs contain the triangle data or triangle ids
- Can create tree down to individual triangle level
 - Requires compression of nodes & bounding boxes to avoid too much memory – see GPG2
- Alternatively create down to a small # of triangles per leaf, like 8 – 20
 - All triangles in leaf will be nearby in memory
 - Argues against storing tri ids, and just vertex indices



- The 'Split Plane' must be intelligently chosen to create a nicely balanced tree
- One approach is to create the AABB tree topdown
 - Create a parent node and find the AABox containing all triangles
 - Split the node somehow into two children
 - Each child gets some of the triangles
 - Each child's AABox may overlap its sibling
 - Recurse into each child until
 - The # of triangles is small enough
 - Or the volume of the AABox is small enough



How To A Node Split into 2 Children?

- A good approach is to pick the largest axis of the AAbox containing all triangles in the parent node
- Then sort the triangles by their centroid with respect to the AABox's largest axis
 - A tall AABox would have its triangles sorted by centroid.y
- Now you can go through exactly half the triangles in the sorted list and give them to the left child, and the assign the rest to the right child
- This gives a median distribution, which guarantees a O(log n) search time



- Modern engines will increasingly use nonsplitting, looser trees with larger numbers of triangles per leaf
- Looser trees, like AABB Trees, and loose Octrees don't split, so they don't increase collision polys needlessly
- A dozen or so triangles per leaf reduce cache misses and amortize the memory cost of the bounding box and node information

Scene Management - Al

- The Al also needs some view of the scene
 - But it should be probably be separate from the rendering & collision views of the world
 - Should probably a simpler, more symbolic view of the world than a collision structure
- The Al will use raycasting and other spatial queries, so this should be fast
 - Line Of Sight
 - Enemies In Range



Question: What is the most expensive render state change?



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Answer: The one that caused you to make more draw calls.



- Question: What is the most expensive render state change?
- Answer: The one that caused you to make more draw calls.
- In general, sort by the item with the most useful coherency.



- You can use the GPU to reduce the number of draw calls needed for your scene.
- Use per-vertex data to encode shading parameters
 - Reduces need to set vertex shader constants
 - Reduces need to switch vertex shaders
 - Example : Indexed Palette Skinning
 - Idea: Apply per-vertex index to other things like lighting, occlusion, etc.

- Use textures to encode shading parameters
 - Reduces need to set pixel shader constants
 - Reduces need to switch pixel shaders
 - Example : Put gloss into the alpha of your normal map, instead of setting it via SetPixelShaderConstant()
 - Idea: Encode 4 light occlusion terms into a lightmap, and draw all 4 shadowed lights in one pass



Lighting and Shadows

- Your choices for Lighting and Shadowing will largely dictate the look and speed of your game
- How dynamic is your lighting?
 - Totally Static
 - Precompute per-vertex or lightmaps
 - Partially Dynamic
 - Lights can change color & intensity, but can't move
 - Build per-light occlusion term into vertex or texture
 - Totally Dynamic
 - Perform plenty of CPU raycasting for shadowing
 - Use GPU-assisted shadows like shadow maps or shadow volumes



Lighting Tradeoffs

Technique	CPU Cost	Vertex Cost	Pixel Cost	Comment
Static Lightmaps	Low, if using texture pages	Low	Low	Any # of lights and shadows free
Dynamic Lightmaps	High, at least when light changes	Low	Low	More lights cost during updates
Dynamic Lightmaps w/ Shadows	Prohibitive	Low	Low	Too many raycasts for CPU

Lighting Tradeoffs

Technique	CPU Cost	Vertex Cost	Pixel Cost	Comment
Occlusion Maps	Low, if using texture pages	Low	Medium	Limits # of lights to 4 or so
Per-Vertex Occlusion	Low	Medium	Low	Lights Can only change color
Stencil Shadows on CPU	High, for batch count and silhouettes	Low	High	Limited to 3 lights per surface

Lighting Tradeoffs

Technique	CPU Cost	Vertex Cost	Pixel Cost	Comment
Stencil Shadows on GPU	Medium for batch size	Very High	High	Limited to 3 lights per surface
Depth Shadow Maps	Low	Medium	Medium	Aliasing Artifacts
PRT via Spherical Harmonics	Low	Medium	Low	Only infinite lights & no animation



Shader Management

- There are two main ways to handle shaders, depending on your type of game
- Open-Ended Artist-driven from within the level editor
 - Highly Flexible
 - Use HLSL / .FX files to manage complexity
 - Somewhat Complex to support many shader types
 - Use Annotations to identify shader parameters
 - Can create explosion of shaders if not careful
 - Switching shaders often is not good for reducing draw calls

Shader Management

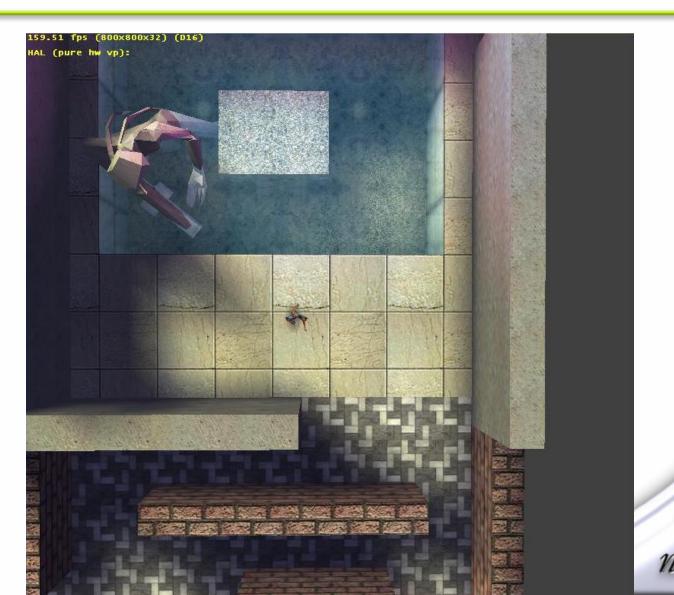
- Unified Shader Model Driven from the Engine Capabilites and/or Game Needs
 - Fewer, more specific, optimized shaders
 - Practical to do C++ coding to set up shaders
 - Can still use .fx files, but not needed as much
 - Shaders are from a more limited set of choices
 - Good for higher framerates by limiting maximum # of draw calls due to shader changes
 - Must build shader parameters into geometry & textures to get the speed benefit



Questions So Far?



Test Engine Overview



Test Engine - Overview

- Top level of the scene is a 3d Grid of 16x16x16 meter cells
 - Triangles are clipped to the grid
 - Each Cell has a Vertex and an Index Buffer
 - AABBTree of collision triangles matching the tessellation of the rendering triangles
 - Also a vector of material records
 - Contains Index Buffer range for triangles
 - Contains AABox for triangles with material
 - List of Moving Entities
 - Contains AABox
 - Contains reference to mesh data for rendering only



Test Engine - Overview

- Advantage to breaking the world into large cells
 - Efficient for culling
 - Can share same VB and IB without going over 65K vertex or triangle limits
 - Can use 16-bit indices for IB
 - Can use 16-bit indices for AABB tree
 - Can compress AABB boxes in tree to 16 or 8 byte per axis and still have good precision
 - Can more quickly reject moving entities in other cells
 - Can restrict lighting to only 7 lights per tile



Many Features, Few Draw Calls

- An entire world cell is drawn in one draw call
 - Up to 7 Lights
 - Diffuse & Specular Bump Mapping
 - Soft shadows
 - Gloss-Mapped, Color Shifted Specular
 - Masked Emissive
 - Water or Fog Depth stored in Dest Alpha
- Fog, Mist and Water are a partial alpha pass
 - Blend in fog layer colors based on dest alpha



Shadows & Deep Water





Test Engine - Lighting

- Shadows for world geometry are pre-calculated for up to 7 lights
- Per-Light occlusion terms are stored in diffuse.rgba and specular.rgb per vertex
- The vertex shader calculates the 7 L vectors
 - Scales the L vectors down by the occlusion & attenuation terms
 - Performs per-vertex N.L.
 - Adds up scaled L vectors



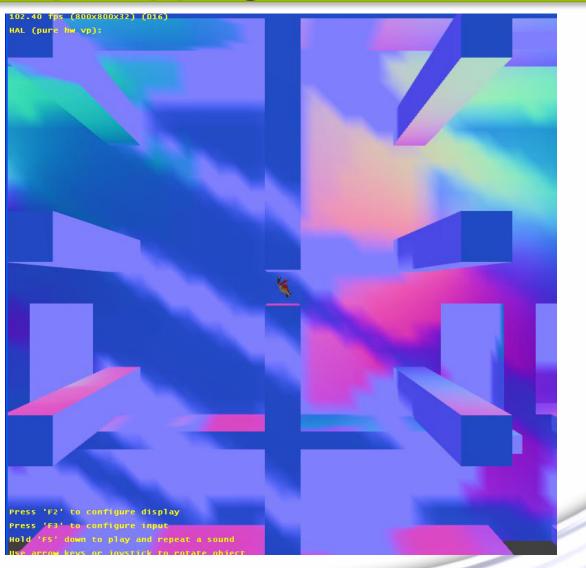
Averaged L Bump Mapping

- The Pixel Shader uses this averaged L vector to perform bump mapping – 'Averaged L Bump Mapping'
- Bump mapping is nice, but not worth it to do for many lights
- This way, if lights change intensity or turn on and off, the bumps respond to the most intense lights
- The bump mapping still corresponds to the scene's lighting, but no need to do up to 7 rendering passes for 7 lights



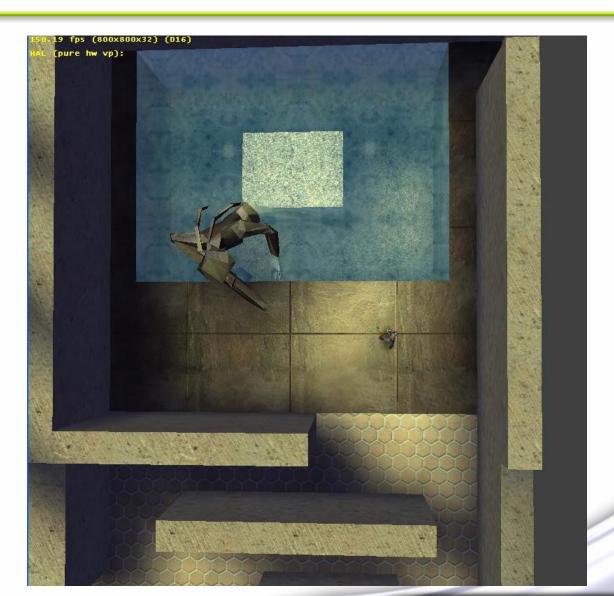
Averaged L Vectors for L Bump Mapping"

"Averaged





Metallic Specular





Questions?

sdietrich@nivida.com

simmer@spies.net

